



Control System for the WS Beam Line and Two-arm Spectrometers

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Collaborators



◆ Constructors

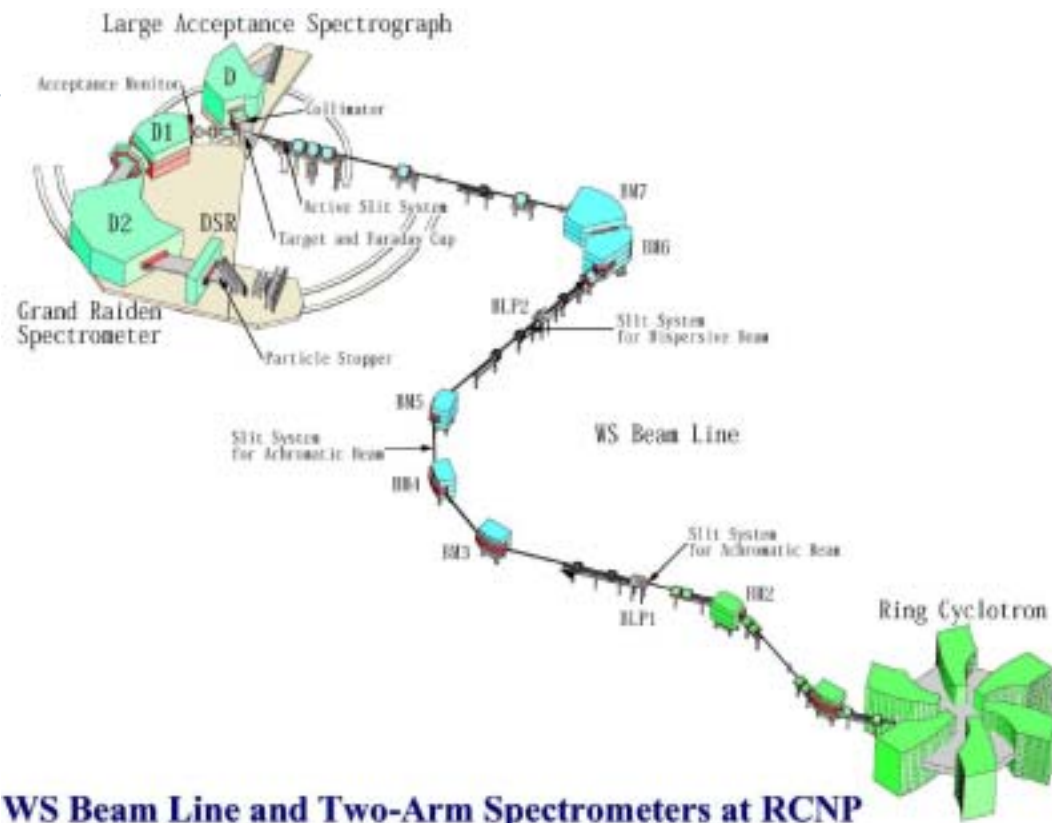
- Y. Sakemi
(Manager)
- M. Uraki
(Hardware)
- T. Wakasa
(Software)

◆ Advisers

- K. Nagayama
(PS, NMR)
- Y. Inata
(SCU)
- K. Tamura
(TCP/IP)
- K. Hatanaka

WS and Two-arm Spectrometers

- ◆ Slit Systems in WS
- ◆ Target & FC in Scattering Chamber
- ◆ Active Slit System in WS and Grand Raiden
- ◆ Particle Stopper
- ◆ Collimator for LAS
- ◆ Spectrometer Control
 - Power Supplies
 - Magnetmeters
 - NMR Probes
 - Hall Probes





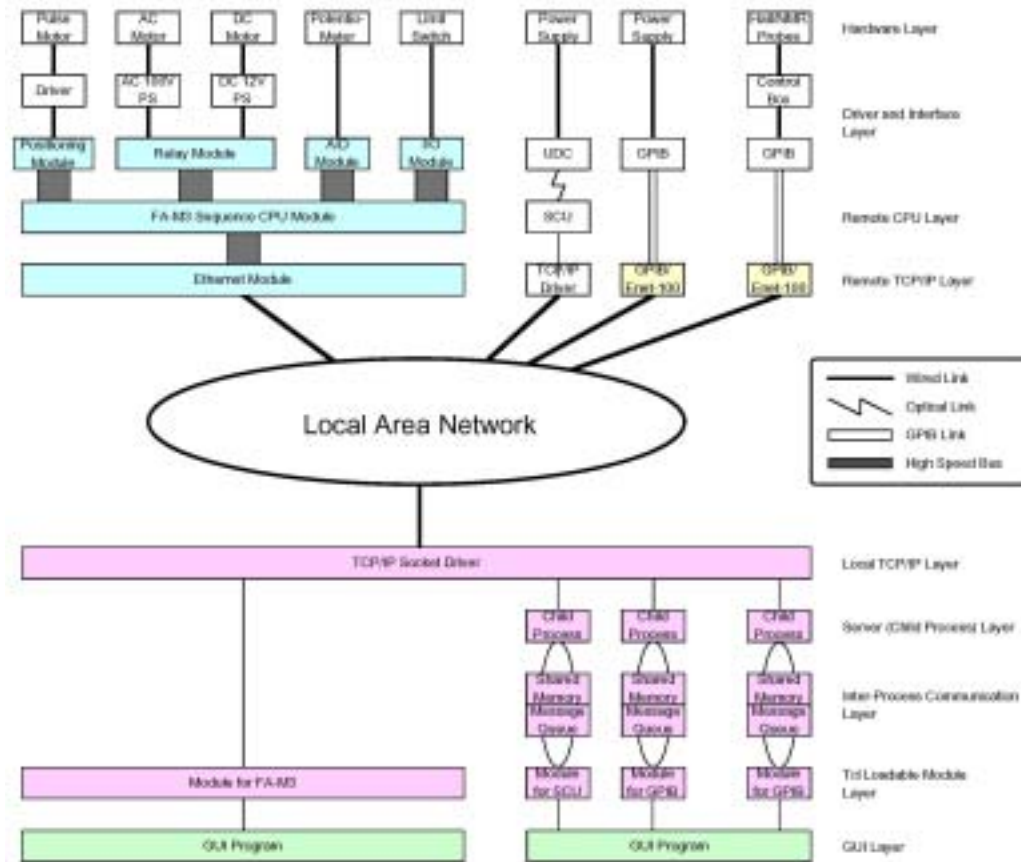
Requirements



- ◆ **Stable and Reliable**
(Hardware (Radiation Damage) and Software)
- ◆ **Flexibility and Scalability**
- ◆ **Open Software and Libraries**
- ◆ **High Performance Feedback System**
- ◆ **Network Capabilities**
- ◆ **Graphical User Interfaces (GUI)**

Layer Scheme of Control System

- ◆ Client/Server system
- ◆ Shared Memory and Message Queue
- ◆ STAR Topology
- ◆ 100M LAN



Future Net FA-11

- *RS232 to Ethernet Interface* -

- ◆ Converter to connect RS232 instruments to the Ethernet (LAN)
- ◆ Up to 460 kbps
- ◆ Use for HV control (between the CAMAC Crate Controller and the Ethernet (LAN))
- ◆ LeCroy HV4032A and REPIC 32010



GUI for HV Control

- ◆ GUI with Tcl/Tk
- ◆ Remote Control with X
- ◆ Control up to 16 Frames
- ◆ Data Load/Save
- ◆ Same Interface for HV4032A and RPH32010
- ◆ Special Thanks to Prof. H. Okamura



Yokogawa FA-M3

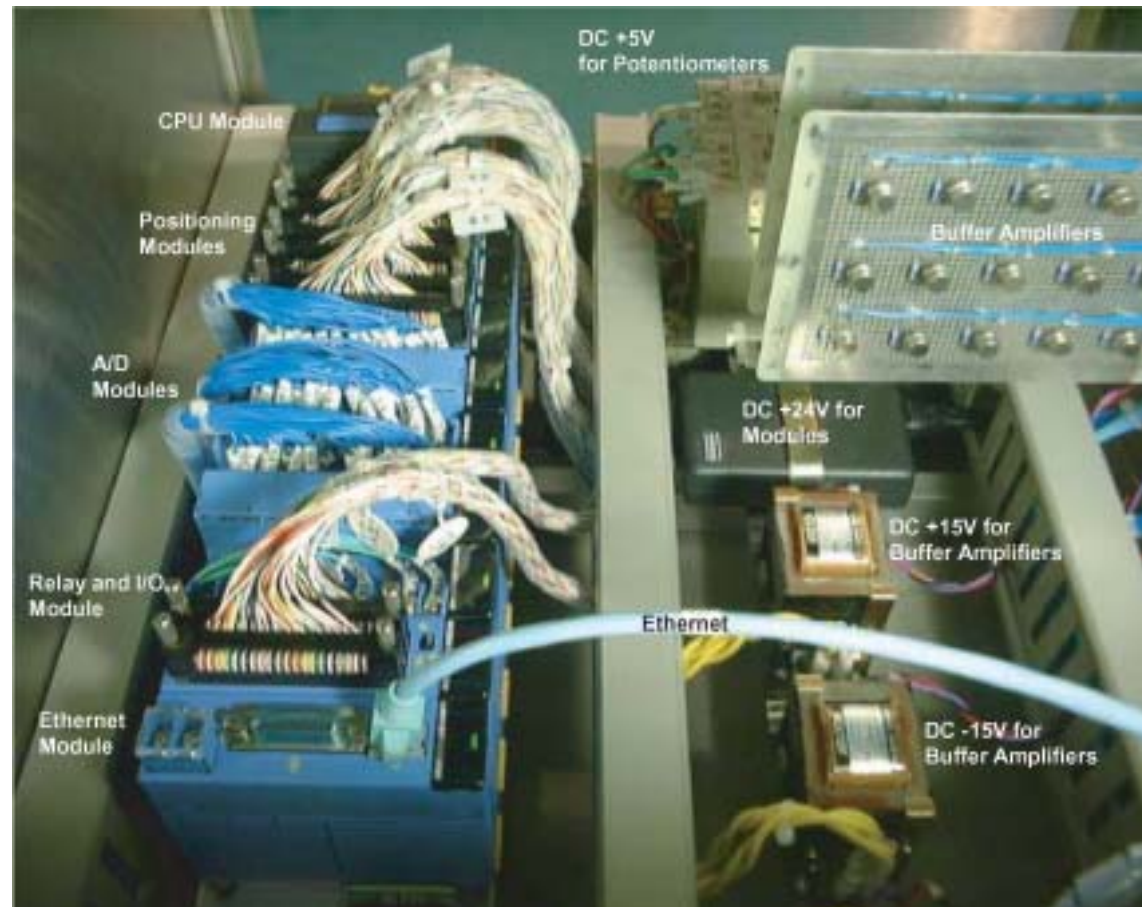
- Motor Control Unit -

- ◆ Fast
 - Calculates 20K steps in 1 ms
 - Minimum scan time is 200 micro-seconds
- ◆ Compact
 - Postcard size
 - Easy to protect from radiation damages
- ◆ Network Capabilities
 - Remote OME (Operation Maintenance and Engineering)



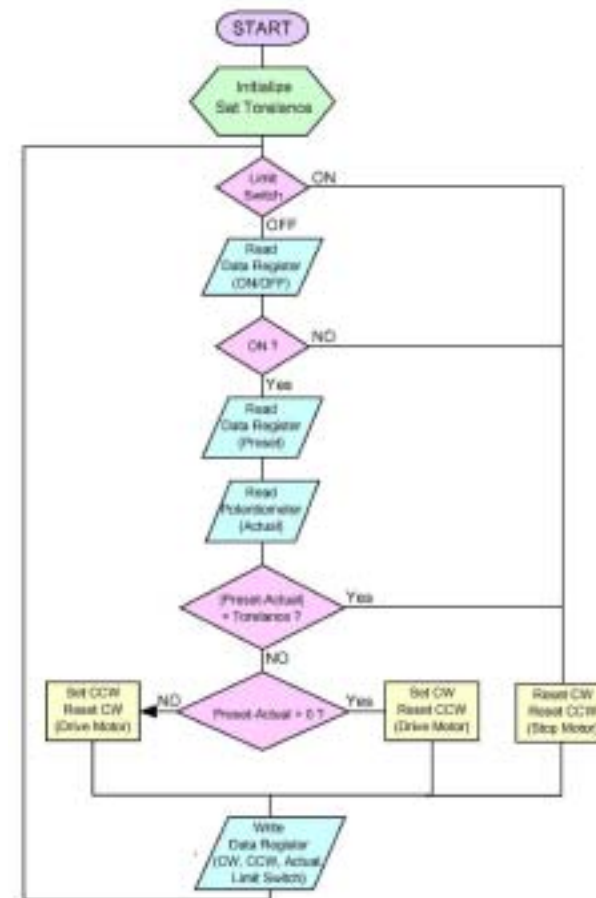
Motor Control Unit

- ◆ Assembled by M. Uraki
- ◆ Control 24 Pulse Motors
- ◆ Control 2 DC Motors
- ◆ Connected to the LAN



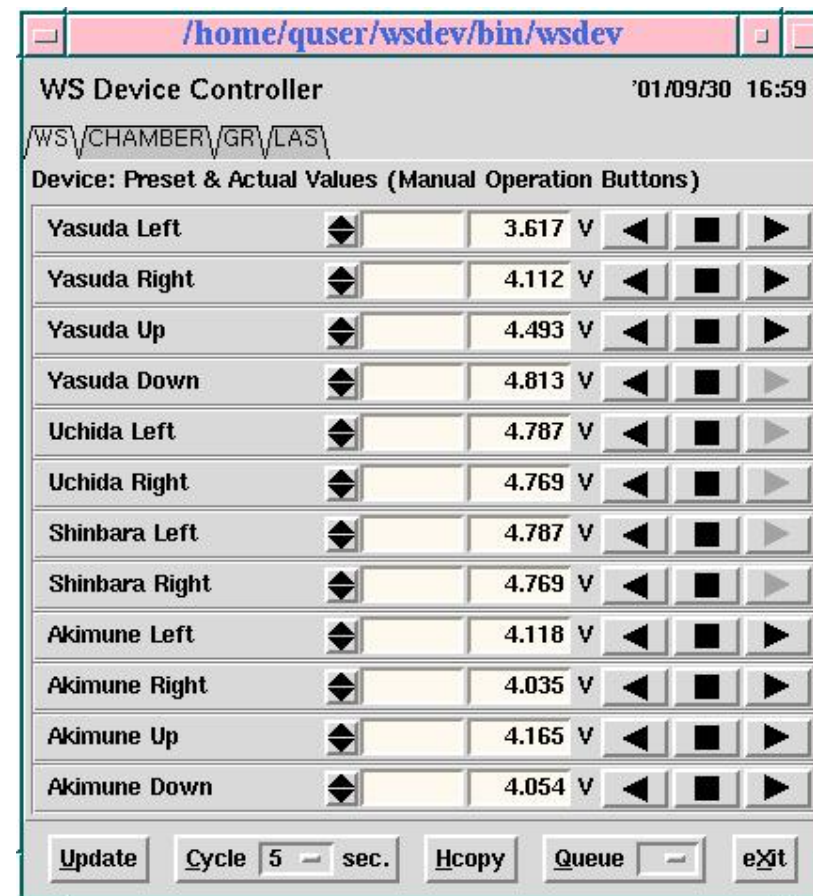
Flow Diagram of Motor Control

- ◆ 24 Pulse Motors for WS and Grand Raiden
- ◆ 2 DC Motors for FC
- ◆ 2 AC Motors for LAS
- ◆ 2 ms for scan
- ◆ Scalable and Flexible



GUI for Motor Control

- ◆ GUI with Tcl/Tk
- ◆ Remote Control with X
- ◆ Scalable and Flexible
- ◆ Special Thanks to Prof. H. Okamura



NI GPIB-Enet/100

- GPIB to Ethernet Interface -

- ◆ Configure and use easily
- ◆ Control GPIB through the network (LAN)
- ◆ Available Linux Driver
- ◆ Transfer data over 800 kB/s



GUI for Spectrometer Control

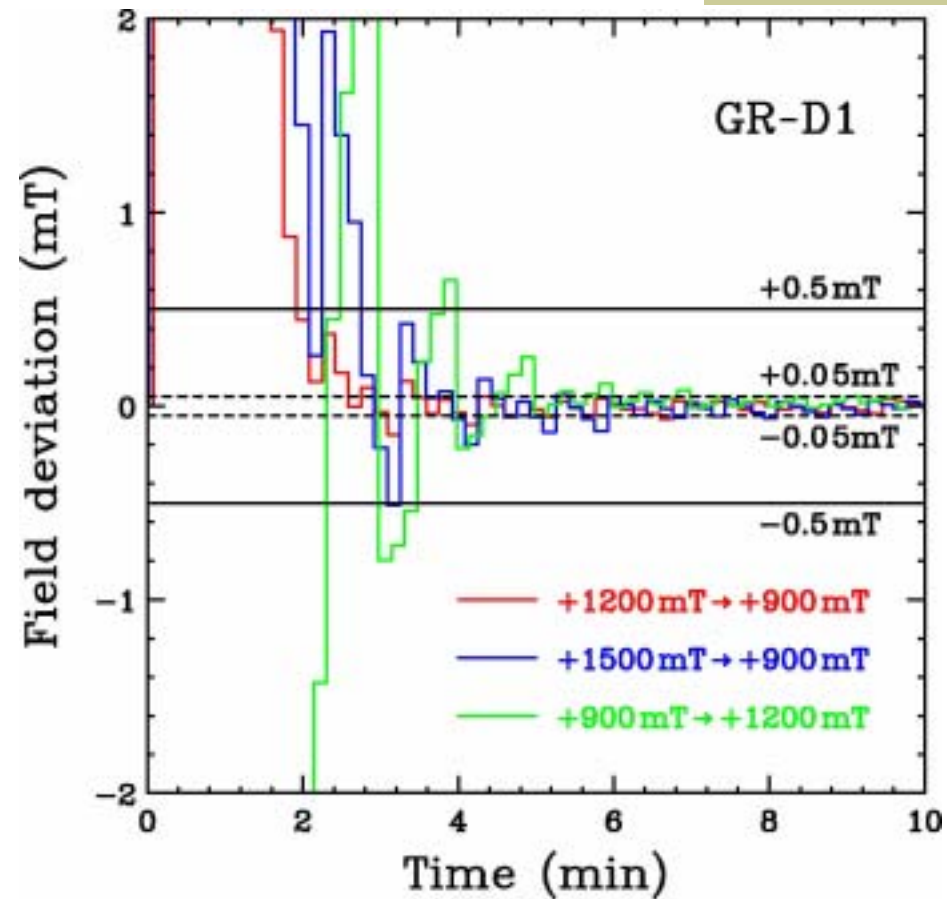
- ◆ GUI with Tcl/Tk
- ◆ Remote Control with X
- ◆ Both Field and Current Settings are available
- ◆ PID Feedback System is implemented
- ◆ Special Thanks to Prof. H. Okamura

The screenshot shows a window titled "WS Magnet Controller" with a timestamp of '01/09/30 17:01'. The window contains a table with columns for Magnet, Field (Preset|Actual), Current (Preset|Actual), Status, PS, NMR, and FB. Below the table are buttons for Update, update Cycle (10 sec.), Hcopy, Queue, and eXit.

Magnet	Field (Preset Actual)	Current (Preset Actual)	Status	PS	NMR	FB
GR Q1		25.10 A	■	■	■	■
GR SX		3.90 A	■	■	■	■
GR Q2		6.70 A	■	■	■	■
GR MQ		6.96 A	■	■	■	■
GR MS		5.02 A	■	■	■	■
GR D1	604.629 mT	159.93 A	■	■	■	■
GR D2	601.398 mT	299.32 A	■	■	■	■
GR DSR	1150.072 mT	131.03 A	■	■	■	■
LAS Q		9.40 A	■	■	■	■
LAS D	-800.214 mT	300.80 A	■	■	■	■

PID Feedback System

- ◆ Supervised by K. Nagayama
- ◆ PID Algorithm
- ◆ Set magnetic field within 0.05 mT after 5 minutes
- ◆ Keep magnetic field within 0.02 mT after 10 minutes





Summary

- ✓ Stable and Reliable
- ✓ Flexible and Scalable
- ✓ Open Software and Libraries with C and Tcl/Tk languages
- ✓ High Performance Feedback System based on a PID Algorithm
- ✓ Remote Control through the LAN
- ✓ User Friendly GUI